

# GENERALIZED NET MODEL OF AN INTUITIONISTIC FUZZY EXPERT SYSTEM WITH FRAME-TYPE DATA BASES AND DIFFERENT FORMS OF HYPOTHESES ESTIMATIONS

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***Abstract:** Series of Generalized Net (GN) models were constructed to describe the way of functioning and the results of the work of different types of Expert Systems (ESs) from production or frame-type data bases. The present GN-model represents the functioning and the results of the work of an ES with frame-type data base with intuitionistic fuzzy evaluations of the frames and of the truth-values of the hypotheses.*

***Key words:** Database, Expert system, Frame, Generalized net, Modelling, Intuitionistic fuzzy set, Evaluation*

## 1. Introduction

Ten Generalized Net (GN, see [3]) models were described in series of papers, collected in book [6]. These GN-models describe the way of functioning and the results of the work of different types of Expert Systems (ESs, see, e.g., [1, 5, 11, 12]). Some types of these ESs are introduced for a first time as possible extensions of the ESs, which extensions can be described by the GNs and can obtain real applications.

The first four from the nine GN-models describe ordinary ESs; the fifth and seventh - ESs with priorities of their Database (DB) facts and Knowledge Base (KB) rules, so, the separate facts and/or rules can be changed at the time of the ES functioning. Sixth GN-model describes an ES containing not only facts but also metafacts that can be represented by rules. In the present form they are more useful and more quickly applicable. Eighth GN-model represents Intuitionistic Fuzzy ES (IFES see [2]; for the intuitionistic fuzziness see [7]). On its base the ninth GN-model is constructed so that it represents functioning of an ES working with temporal facts and answering to the temporal questions [4]. The tenth GN-model (see [8]) represents extension to the later ES. In [10] is described GN-model of ESs with Frame-Type Data Bases (FTDB). It is extended in [A] by adding intuitionistic fuzzy estimations of the frames.

The present paper is an expansion of the research from [9]. Now, we will discuss the possibility to evaluate the truth-values of the hypotheses by three estimations types: optimistic, average and pessimistic. Another interpretation of the intuitionistic fuzzy estimations will be given, different from the one in [9].

The frame is an aggregate of attributes and connected values that describes world's entities. The frame-systems are connected combinations of frames.

Every statement, represented by frame, enters in Frame-Type Data Base with rate of the coincidence, represented by intuitionistic fuzzy estimation  $\langle \mu, \nu \rangle$  of real numbers from the set  $[0,1] \times [0,1]$  and

$$0 \leq \mu + \nu \leq 1.$$

This estimation (one for the frame) can be determined by the values of the slots in the frame, if each slot has own intuitionistic fuzzy estimation.

The number  $\pi = 1 - \mu - \nu$  corresponds to the degree of the frame uncertainty.

## 2. A GN-model

The GN-model of ES with FTDB is shown on Fig. 1.

Let  $\Delta$  be the Frame-Type Data Base (FTDB) of a given ES. Each frame is an ordered set of slots and each slot is an ordered couple:  $\langle A, V \rangle$ , where  $A$  is an attribute and  $V$  is its value. In the present paper we will suppose that the value can be single value or method, rule or trigger that calculates this value. Here we will suppose that the intuitionistic fuzzy estimations of the frames will be calculated on the basis of the slot estimations, or, that they are determined in beginning by the users.

For clarity the places are marked by three different symbols:  $a$ ,  $b$  and  $e$  such that:

- $\alpha$ -tokens ( $\alpha_1, \alpha_2, \dots$ ) together with their descendants of all generations obtained after splitting will go to the  $a$ -places;

- $\beta$ -tokens ( $\beta_1, \beta_2, \dots$ ) will go to  $b$ -places;

- $\beta_0$ -token permanently stays in place  $b_3$  with initial characteristic

$$x_0^{\beta_0} = \langle \Delta \rangle,$$

*i.e.*,  $x_0^{\beta_0}$  is a set of frames and  $j$ -th frame of  $\Delta$  will have intuitionistic fuzzy estimation

$\langle \mu_j, \nu_j \rangle$ ;

- $\gamma$ -token will stays permanently in place  $e_1$ .

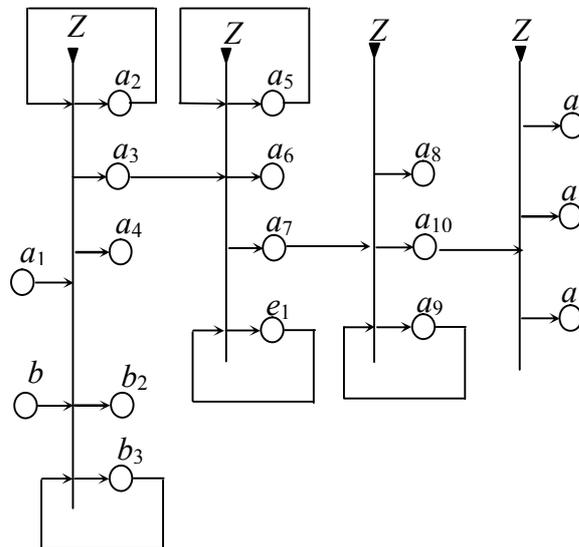


Fig. 1: GN-model of ESs with FTDB with evaluations of the frames

Let current  $\alpha$ -token ( $\alpha_p$ ) enters place  $a_1$  of the GN with an initial characteristic  $x_0^{\alpha_p} = "H"$ ,

where  $p$  is the current number of the  $\alpha$ -token which enters place  $a_1$  and  $H$  is a hypothesis (goal). Let  $x_{cu}^{\alpha_i}$  denotes the current characteristic of the  $\alpha_i$ -token.

The transitions of the GN are the following (see Fig. 1).

$Z_1 = \langle \{a_1, a_2, b_1, b_3\}, \{a_2, a_3, a_4, b_2, b_3\}, r_1, \wedge(\vee(a_1, a_2), \vee(b_1, b_3)) \rangle$ ,  
where

$r_1 =$	$a_2$	$a_3$	$a_4$	$b_2$	$b_3$
$a_1$	$r_{a_1, a_2}$	$r_{a_1, a_3}$	$r_{a_1, a_4}$	<i>false</i>	<i>false</i>
$a_2$	$r_{a_2, a_2}$	$r_{a_2, a_3}$	<i>false</i>	<i>false</i>	<i>false</i>
$b_1$	<i>false</i>	<i>false</i>	<i>false</i>	<i>false</i>	<i>true</i>
$b_3$	<i>false</i>	<i>false</i>	<i>false</i>	$r_{b_3, b_2}$	$r_{b_3, b_3}$

and

$r_{a_1, a_2} = r_{a_2, a_2} =$  "There are more than one frame with a slot having the searching attribute that is not used by the moment for the current token",

$r_{a_1, a_3} = r_{a_2, a_3} =$  "There is a frame with a slot having the searching attribute",

$r_{a_1, a_4} =$  "There is no frame with a slot having the searching attribute",

$r_{b_3, b_2} =$  "There are no  $\alpha$ -tokens for processing",

$r_{b_3, b_3} = \neg r_{b_3, b_2}$ .

The  $\alpha$ -tokens can split to two tokens – the same token  $\alpha$  and another  $\alpha$ -token. The token in place  $a_3$  obtains the characteristic

$x_1^\alpha =$  "number of the suitable frame (let it be  $j$ -th frame of  $\Delta$ ), its intuitionistic fuzzy evaluations  $\langle \mu_j, \nu_j \rangle$ "

and the characteristic

$$" \neg ! x_0^\alpha, \langle 0, 1 \rangle "$$

that symbolizes that the hypothesis is not valid, in place  $a_4$ . The other  $\alpha$ -token (if such exists) does not obtain any characteristic in place  $a_2$ .

When there is  $\beta$ -token in place  $b_1$  on the next time-step  $\beta_0$ -token obtains the characteristic

$$x_{cu}^{\beta_0} = \begin{cases} \left( x_{cu-1}^{\beta_0} - [x_0^{\beta_j}] \right) \cup \{x_0^{\beta_j}\} & , \text{ if in the DB there is a frame with key } x_0^{\beta_j} \\ x_{cu-1}^{\beta_0} \cup \{x_0^{\beta_j}\} & , \text{ otherwise} \end{cases}$$

where  $[x_0^{\beta_j}]$  denotes the frame of  $\Delta$  which has the same key as the frame  $x_0^{\beta_j}$  and

$$x_0^{\beta_j} = \text{"frame, } \langle \mu_j, v_j \rangle \text{"}$$

$$Z_2 = \langle \{a_3, a_5, e_1\}, \{a_5, a_6, a_7, e_1\}, r_2, \vee(a_3, a_5, e_1) \rangle,$$

where

	$a_5$	$a_6$	$a_7$	$e_1$
$a_3$	<i>false</i>	<i>false</i>	<i>false</i>	<i>true</i>
$a_5$	<i>false</i>	<i>false</i>	<i>false</i>	<i>true</i>
$e_1$	$r_{e_1, a_5}$	$r_{e_1, a_6}$	$r_{e_1, a_7}$	<i>true</i>

and

$r_{e_1, a_5}$  = "The slot value (method, rule or trigger) of the current frame must be calculated by a procedure",

$r_{e_1, a_6}$  = "The frame values are not satisfactory",

$r_{e_1, a_7}$  = "The frame values are satisfactory".

The characteristic of the  $\gamma$ -token from place  $e_1$  contains two threshold values for the  $\mu_j$  ( $M_{min}$  and  $M_{max}$ ) and two threshold values for the  $v_j$  ( $N_{min}$  and  $N_{max}$ ).

If  $\mu_j > M_{max}$  &  $v_j < N_{min}$ ,

then the  $\alpha$ -token enter in place  $a_7$  without a new characteristic.

If  $\mu_j < M_{min}$  &  $v_j > N_{max}$ ,

then the  $\alpha$ -token enter in place  $a_6$  and if there is only one  $\alpha$ -token in the net, then it

obtains the characteristic " $\neg ! x_0^\alpha, \langle \mu_j, v_j \rangle$ ".

If there are more than one  $\alpha$ -token in the net, then the present one leaves the net without any characteristic.

In the rest case the current  $\alpha$ -token enters place  $a_5$  and obtains the characteristic

"new frame value, obtained by the determined method, rule or trigger".

$$Z_3 = \langle \{a_7, a_9\}, \{a_8, a_9\}, r_3, \vee(a_7, a_9) \rangle,$$

where

	$a_8$	$a_9$	$a_{10}$
$a_7$	$r_{a_7, a_8}$	$r_{a_7, a_9}$	<i>false</i>
$a_9$	<i>false</i>	$r_{a_9, a_9}$	$r_{a_9, a_{10}}$

and

$r_{a_7, a_8}$  = "There are no other  $\alpha$ -tokens in the GN outside place  $a_7$ ",

$r_{a_9, a_{10}}$  = "There are no other  $\alpha$ -tokens in the GN outside place  $a_9$ ",

$r_{a_7, a_9} = \neg r_{a_7, a_8}$ ,

$r_{a_9, a_9} = \neg r_{a_9, a_{10}}$ .

The current  $\alpha$ -token enters place  $a_9$  where eventually there are other  $\alpha$ -tokens. All they will merge in this place and the current token will obtain as a characteristic " $\langle$ list of used frames, list of their intuitionistic fuzzy estimations $\rangle$ ".

The token does not obtain any characteristic in places  $a_8$  and  $a_{10}$ .

$$Z_4 = \langle \{a_{10}\}, \{a_{11}, a_{12}, a_{13}\}, r_4, \vee(a_{10}) \rangle,$$

$$r_4 = \frac{\begin{array}{c|ccc} & a_{11} & a_{12} & a_{13} \\ \hline a_{10} & r_{10,11} & r_{10,12} & r_{10,13} \end{array}}{\quad}$$

and

$r_{10,11}$  = “an optimistic evaluation is necessary”,

$r_{10,12}$  = “an average evaluation is necessary”,

$r_{10,13}$  = “a pessimistic evaluation is necessary”.

Let the list of the intuitionistic fuzzy estimations from the last  $\alpha$ -token characteristic be

$$\langle \mu_1, \nu_1 \rangle, \langle \mu_2, \nu_2 \rangle, \dots, \langle \mu_s, \nu_s \rangle,$$

where  $s$  is the number of the used frames, collected in the last  $\alpha$ -token characteristic.

Then the  $\alpha$ -token obtains in place  $a_{11}$  the characteristic

$$\text{“! } x_0^\alpha, \left\langle \max_{1 \leq i \leq s} \mu_i, \min_{1 \leq i \leq s} \nu_i \right\rangle\text{”},$$

in place  $a_{12}$  the characteristic

$$\text{“! } x_0^\alpha, \left\langle \frac{1}{s} \sum_{i=1}^s \mu_i, \frac{1}{s} \sum_{i=1}^s \nu_i \right\rangle\text{”},$$

and in place  $a_{13}$  the characteristic

$$\text{“! } x_0^\alpha, \left\langle \min_{1 \leq i \leq s} \mu_i, \max_{1 \leq i \leq s} \nu_i \right\rangle\text{”}.$$

### 3. Conclusion

The described GN is a model of special class of ES, using intuitionistic fuzzy evaluations. In the present paper there are some restrictions on the form of the frames, but in the next authors' research a GN-model of an ES with FTDB without the limitations will be described. Some extensions of the form of the ES with FTDB will be discussed also.

In the future, the presented GN can be worked out in detail, using hierarchical operators which replace a given transition or a place by a complete GN that has the same, but detailed behaviour. The presence of the temporal intuitionistic fuzzy evaluations [4] in the characteristics of the tokens enables various analysis and statistical techniques to be applied to the process of working. The purpose of such analysis would be to generate ideas for improving and optimizing the process.

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